

Getting Started

Now you have assembled your BoBBot it's time to program your micro:bit to control it. Here is an example program written in different languages, it's designed to make BoBBot move forward and backward for 2 seconds.

The online editors can be accessed here: microbit.org/code

Microsoft Touch Develop

script BoBBot Example

function main ()

{ pins → digital write pin(P16, 1)

{ pins → digital write pin(P12, 1)

{ basic → pause(2000)

{ pins → digital write pin(P16, 0)

{ pins → digital write pin(P12, 0)

{ pins → digital write pin(P8, 1)

{ pins → digital write pin(P0, 1)

{ basic → pause(2000)

{ pins → digital write pin(P8, 0)

{ pins → digital write pin(P0, 0)

end function

Python

```
from microbit import *
```

```
#gives the pins descriptive names
rightFwd=pin16
leftFwd=pin12
rightBck=pin8
leftBck=pin0
lineSensor=pin1
```

```
#both motors forward for 2 secs
rightFwd.write_digital(1)
leftFwd.write_digital(1)
sleep(2000)
rightFwd.write_digital(0)
leftFwd.write_digital(0)
```

```
#both motors backward for 2 secs
rightBck.write_digital(1)
leftBck.write_digital(1)
sleep(2000)
rightBck.write_digital(0)
leftBck.write_digital(0)
```

Microsoft Block Editor

Moves both motors forward for 2 seconds

digital write (0,1) 1 to pin P16

digital write (0,1) 1 to pin P12

pause (ms) 2000

digital write (0,1) 0 to pin P16

digital write (0,1) 0 to pin P12

digital write (0,1) 1 to pin P8

digital write (0,1) 1 to pin P0

pause (ms) 2000

digital write (0,1) 0 to pin P8

digital write (0,1) 0 to pin P0

Moves both motors backward for 2 seconds